

Title: Method, Program and System of Forming Visual...

Inventor(s): Morito MORISHIMA, et al. Application No.: Not yet assigned Docket No.: 393032041900

FIG. 2

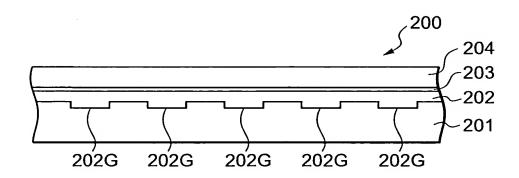


FIG. 3

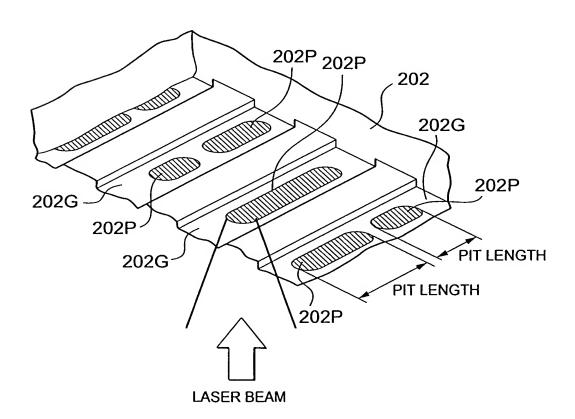


FIG. 4

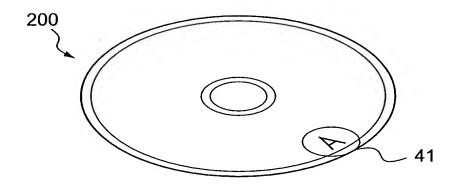


FIG. 5

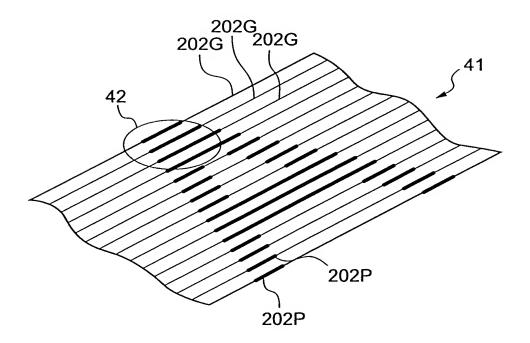


FIG. 6

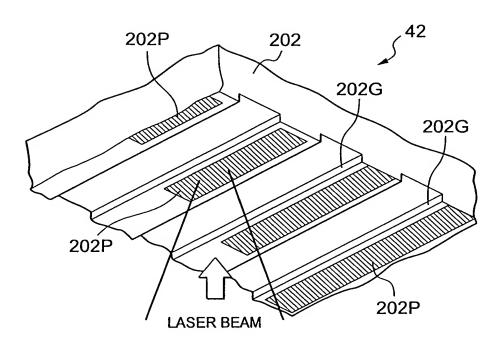


FIG. 7

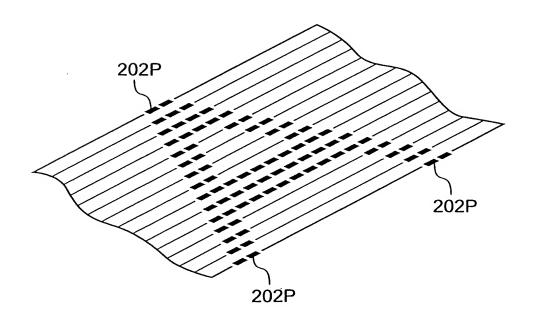
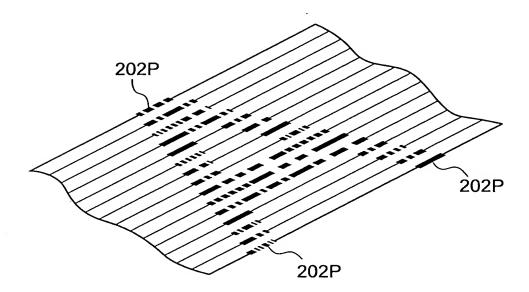


FIG. 8



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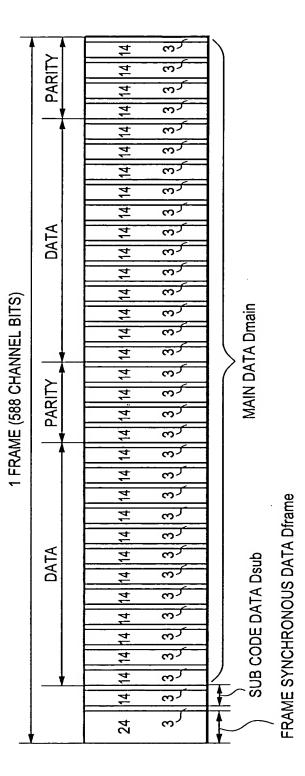


FIG. 10

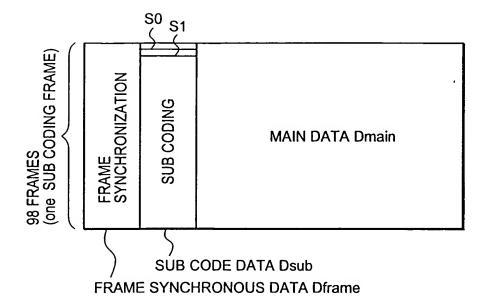


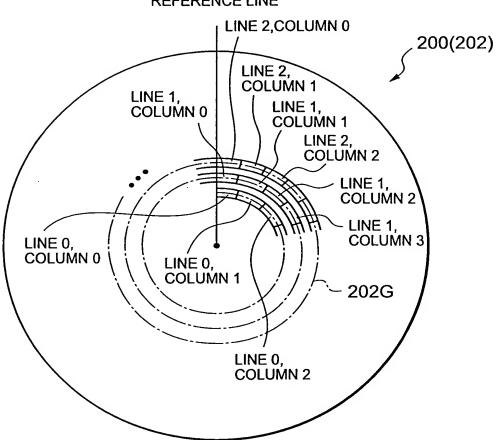
FIG. 11

FRAME NO. 1				S0					
2				S1					
3	P1	Q1	R1	S1	T1	U1	V1	W1	
4	P2	Q2	R2	S2	T2	U2	V2	W2	
5				•					one SUB
6				•					CODING
•				•					FRAME
95	P93	Q93	R93	S93	T93	U93	V93	W93	
96	P94	Q94	R94	S94	T94	U94	V94	W94	
97	P95	Q95	R95	S95	T95	U95	V95	W95	
98	P96	Q96	R96	S96	T96	U96	V96	W96	
1				S0					
2				S1					
•	P1	Q1	R1	S1	T1	U1	V1	W1	
•	P2	Q2	R2	S2	T2	U2	V2	W2	
				•					
				<u> </u>					

SIBLE IMAGE	TA Dx			(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)		(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	•	• •	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)
DETAILS OF VISIBLE IMAGE	FORMATION DA	SO	S1	PWM1	PWM2		PWM4	PWM5	PWM6	PWM7	PWM8	PWM9) PWM10	I PWM11	2 PWM12	3 PWM13	1 PWM14	5 PWM15	3 PWM16	7 PWM17	3 PWM18			3 PWM93	t PWM94		S PWM96
				Cm1	Cm2	Cm3	Cm4	Cm5	Cm6	Cm7	Cm8	6WO	Cm10	Cm11	Cm12	Cm13	Cm14	Cm15	Cm16	Cm17	Cm18	•	••	Cm93	Cm94	Cm95	Cm96
																											-
qua	ane			W1	W2	W3	W4	W5	9/\	LM	8M	6M	01W	11M	W12	W13	W14	W15	91M	21 M	W18	•	••	W93	W94	36M	96M
DETAILS OF SLIB CODE DATA Deub	אואל			• • •	•••	•••	•••	•••	• • •	•••	• • •	•••	• • •	• • •	• • •	• • •	•••	•••	• • •	• • •	• • •	•	••	•••	• • •	•••	• • •
ם מ		0	7	S1	S2	S3	S4	SS	S 6	S7	S8	88	S10	S11	S12	S13	S14	S15	S16	S17	S18	•	• •	S93	S94	S95	96 S
a U	300	SO	S1	R1	R2	R3	R4	R5	R6	R7	R8	R9	R10	R11	R12	R13	R14	R15	R16	R17	R18	•	••	R93	R94	R95	R96
0	200			Q1	Q2	Q3	Q4	Q5	Q 6	۵7	90	60	Q10	Q11	Q12	Q13	Q14	Q15	Q16	Q17	Q18	•	••	693	Q94	Q95	Q96
7	- - - - -			P1	P2	Р3	P4	P5	9d		P8	P9	P10	P11	P12	P13	P14	P15	P16	P17	P18	•	••	P93	P94	P95	96d
FRAME	NO.	1	2	3	7	5	9	7	œ	6	10	11	12	13	14	15	16	17	18	19	20	•	••	95	96	26	86

FIG. 13

REFERENCE LINE



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FIG. 14

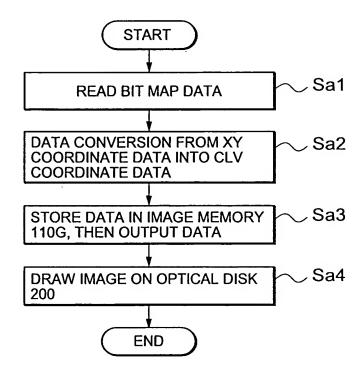


FIG. 15(a)

FIG. 15(b)

RECTANGULAR COORDINATES

SYATION

Title: Method, Program and System of Forming Visual...

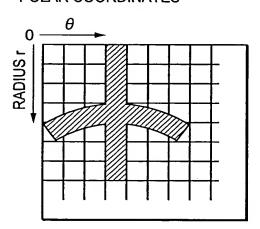
Inventor(s): Morito MORISHIMA, et al. Application No.: Not yet assigned

Docket No.: 393032041900

FIG. 16(a)

FIG. 16(b)

POLAR COORDINATES



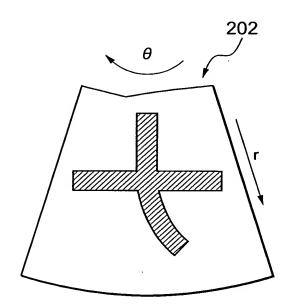
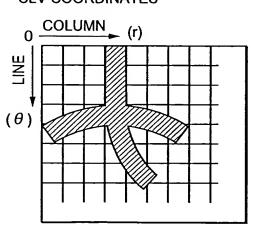
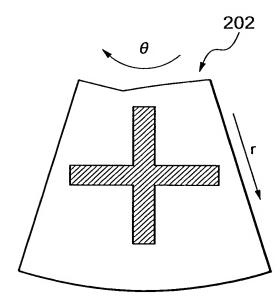


FIG. 17(a)

FIG. 17(b)

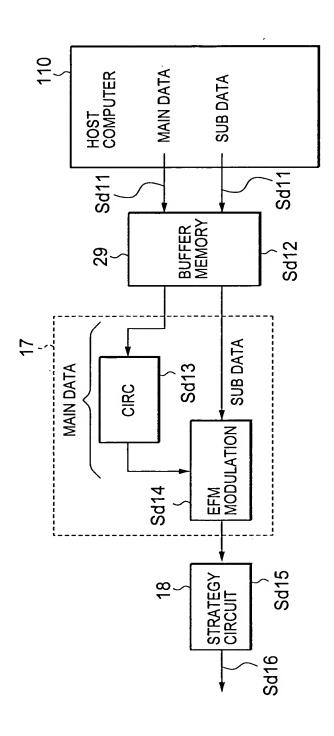
CLV COORDINATES





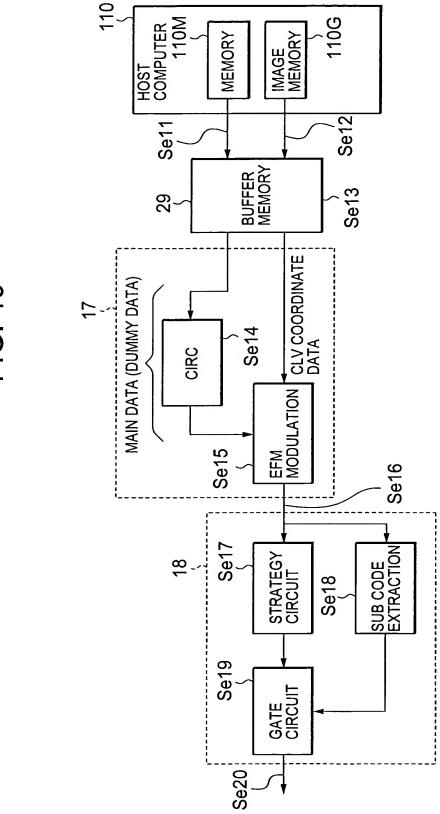
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Application No.: Not yet assigned Docket No.: 393032041900



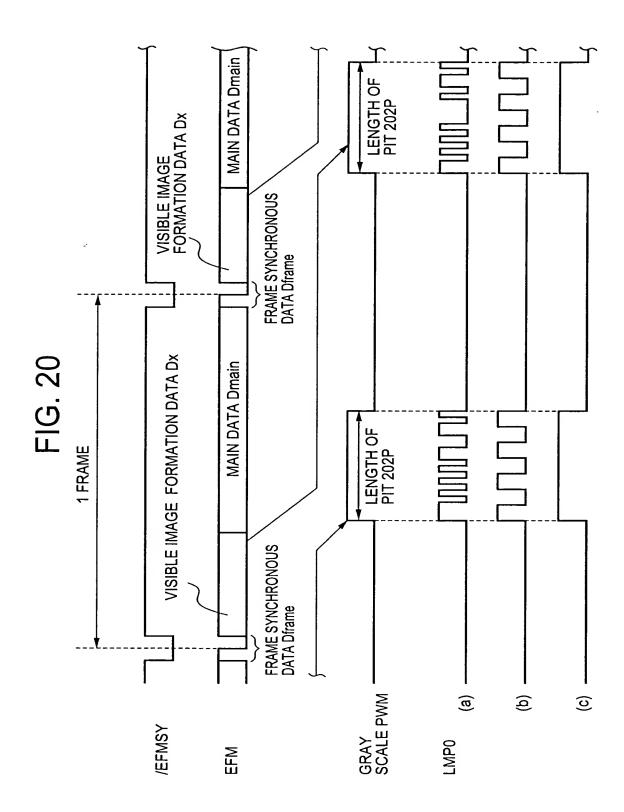
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Application No.: Not yet assigned Docket No.: 393032041900



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E IMAGE Dx			$(0,1,2)\times 2$	$(0,1,2) \times 2$	$(0,1,2)\times 2$	$(0,1,2)\times 2$	$(0,1,2)\times 2$	$(0,1,2)\times 2$	$(0,1,2) \times 2$	$(0,1,2) \times 2$	$(0,1,2) \times 2$	$(0,1,2) \times 2$	$(0,1,2)\times 2$	$(0,1,2)\times 2$	$(0,1,2)\times 2$	$(0,1,2)\times 2$	$(0,1,2) \times 2$	$(0,1,2) \times 2$	$(0,1,2)\times 2$	$(0,1,2) \times 2$	•	• •	$(0,1,2) \times 2$	$(0,1,2) \times 2$	$(0,1,2) \times 2$	$(0,1,2) \times 2$
DETAILS OF VISIBLE IMAGE FORMATION DATA DX	S0	S1	PWM1	PWM2	PWM3	PWM4	PWM5	PWM6	PWM7	PWM8	PWM9	PWM10	PWM11	PWM12	PWM13	PWM14	PWM15	PWM16	PWM17	PWM18			PWM93	PWM94	PWM95	PWM96
ETAIL ORM/			0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	•	••	0	0	0	0
			Cm1	Cm2	Cm3	Cm4	Cm5	Cm6	Cm7	Cm8	Cm9	Cm10	Cm11	Cm12	Cm13	Cm14	Cm15	Cm16	Cm17	Cm18	•	••	Cm93	Cm94	Cm95	Cm96
				_																			T	í		
qns(W1	W2	M3	W4	5M	9//	2M	W8	6M	W10	W11	W12	W13	W14	W15	W16	W17	W18	•	••	W93	W94	26M	96/
DATA [•••	•••	• • •	•••	• • •	• • •	• • •	•••		• • •	• • •	•••	•••	•••	•••	•••	• • •	•	•	••	:	•••	•••	:
DETAILS OF SUB CODE DATA Dsub	So	1	S1	S2	S3	84	SS	98	2 S	88	68	S10	S11	S12	S13	S14	S15	S16	217	S18	•	••	S93	894	895	96S
F SUB	S	S1	R1	R2	R3	R4	RS	B 8	L	88	R9	R10	R11	R12	R13	R14	R15	R16	R17	R18	•	••	R93	R94	R95	R96
AILS 0			ဝ	Q 2	Q3	Q4	Q5	Q6	07	90	60	Q10	Q11	Q12	Q13	Q14	Q15	Q16	Q17	Q18	•	••	093	Q94	095	960
DET			7	P2	P3	P4	P5	_9d	P7	P8	P9	P10	P11	P12	P13	P14	P15	P16	P17	P18	•	••	P93	P94	P95	96d
FRAME NO.	-	2	က	4	2	9	7	8	6	9	-	12	13	14	15	16	17	18	19	20	•	••	95	96	97	98

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MAGE			(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	•	••	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)	(0,1,2,3,4,5,6)
OF VISIBLE IMAGE ON DATA Dx			PWM1	PWM2	PWM3	PWM4	PWM5	PWM6	PWM7	PWM8	PWM9	PWM10	PWM11	PWM12	PWM13	PWM14	PWM15	PWM16	PWM17	PWM18			PWM93	PWM94	PWM95	PWW96
DETAILS OF Y	S0	S1	Cm1	Cm2	Cm3	Cm4	Cm5	Cm6	Cm7	Cm8	Cm ₉	Cm10	Cm11	Cm12	Cm13	Cm14	Cm15	Cm16	Cm17	Cm18	•	• •	Cm93	Cm94	Cm95	Cm96
DET, FOR			Ď	α5	Q 3	Q	Q 5	90	۵7	90	60	Q10	011	Q12	Q13	Q14	Q15	Q16	Q17	Q18	•	••	093	Q94	Q95	960
			P1	P2	РЗ	P4	P5	9e	Ъ7	P8	P9	P10	P11	P12	P13	P14	P15	P16	P17	P18	•	••	P93	P94	P95	96d
															_					~			~	4		
			W1	W2	W3	W4	3/1	9/\	LM.	8/M	6/\	W10	M11	W12	W13	W14	M15	W16	W17	W18	•	• •	W93	W94	36M	96/
DATA Dsub			W1	••• W2	••• W3	W4	SW •••	9M •••	ZM •••	8M	6M ···	W10	W11	· · · W12	W13	••• W14	••• W15	W16	••• W17	••• W18	• •	· ·	:6M	6M ⋅・・	6M •••	96M · · ·
CODE DATA Dsub	00	19		•	•	•	•	•	•	•	•••	•	•	•		•	•	•	S17 ••• W17		•	•••	•	•		-
JF SUB CODE DATA Dsub	S0	S1	•••	•••	• • •	• • •	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•	•	•••	:	•	•••	:
AILS OF SUB CODE DATA Dsub	80	S1	S1 •••	S2 •••	S3 •••	S4 ···	S5 •••	••• 9S	S2	S8	••• 6S	S10 ···	S11 ···	S12 ···	S13 ···	S14 ···	S15 ···	S16 •••	S17 ···	S18 •••	•	•••	S93 •••	894 •••	R95 S95 •••	••• 96S
DETAILS OF SUB CODE DATA Dsub	0S	S1	R1 S1 •••	R2 S2 ···	R3 S3 •••	R4 S4 •••	R5 S5 •••	R6 S6 •••	R7 S7 •••	R8 S8 •••	R9 S9 •••	R10 S10 ···	R11 S11 ···	R12 S12 •••	R13 S13 ···	R14 S14 ···	R15 S15 •••	R16 S16 •••	R17 S17 •••	R18 S18 •••	•	•••	R93 S93 •••	R94 S94 •••	R95 S95 •••	R96 S96